

How (Not) To Train Your DNN Using The Information Bottleneck Functional



The Authors and Funders



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Setup and Notation

$$Y \longrightarrow X \longrightarrow \begin{bmatrix} encoder \\ f_{\theta} \end{bmatrix} \xrightarrow{L} \begin{bmatrix} decoder \\ h_{\psi} \end{bmatrix} \xrightarrow{decision} \begin{bmatrix} decision \\ rule \end{bmatrix} \longrightarrow \hat{Y}$$

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▶
$$Y \in \mathcal{Y}$$
, \mathcal{Y} finite set

►
$$X \in \mathbb{R}^N$$

Encoder and decoder are deterministic, e.g.,

$$L_{i+1} = \sigma \left(\mathbb{W}_i^T L_i + b_{i+1} \right)$$

and $\theta = \{ \mathbb{W}_0, \dots, \mathbb{W}_{i-1}, b_1, \dots, b_i \}$

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Intermediate representation *L* should

P1 Contain sufficient info for classification (DPI!)

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 $P1 \Leftrightarrow \text{large } I(Y; L)$ $P2 \Leftrightarrow \text{small } I(X; L)$

IB principle for training DNNs¹

$$\min_{\theta} I(X; L) - \beta I(Y; L)$$

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 $^{^1\}mathsf{T}\mathsf{ishby}$ and Zaslavsky, "Deep learning and the information bottleneck principle", 2015

²Kolchinsky, Tracey, and Wolpert, Nonlinear Information Bottleneck, 2018

³Alemi et al., "Deep Variational Information Bottleneck", 2017

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$$\min_{\theta} I(X; L) - \beta I(Y; L)$$

Approximations yield^{2,3}

- simple latent representation
- improved generalization
- adversarial robustness



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taken from [2]

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Do we have $(P1 \land P2) \implies (P3 \land P4)$?

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▶ Focus on P1 and P2, defined via mutual information

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- Optimizable?

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- Computable?
- Optimizable?
- Invariant under bijections

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Focus on the encoder f_{θ} , decoder (P3!) not considered

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▶ Focus on P1 and P2, defined via mutual information

- Computable?
- Optimizable?
- Invariant under bijections
- Focus on the encoder f_{θ} , decoder (P3!) not considered
- ▶ (Focus on *L*, architectural simplicity not considered)

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Computability

Theorem

Let X have a PDF f_X that is continuous on $\mathcal{X} \subset \mathbb{R}^N$.

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Theorem

Let X have a PDF f_X that is continuous on $\mathcal{X} \subset \mathbb{R}^N$. Let σ be either bi-Lipschitz or continuously differentiable with strictly positive derivative.

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Computability

Theorem

Let X have a PDF f_X that is continuous on $\mathcal{X} \subset \mathbb{R}^N$. Let σ be either bi-Lipschitz or continuously differentiable with strictly positive derivative. Then, for almost every choice of θ , we have

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 $I(X; L) = \infty.$

Let X have a discrete distribution \implies IB functional is finite

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- \blacktriangleright IB functional is a piecewise constant function of θ
- Cannot use gradient-based optimization techniques

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Invariance under Bijections: No P3



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Invariance under Bijections: No P4



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IB for Learning Representations – Summary

The IB functional

- is infinite for continuous input
- is piecewise constant in general
- does not encourage "simple" representations (P3)
- does not encourage robust representations (P4)

Why does it work?4,5

⁴Kolchinsky, Tracey, and Wolpert, Nonlinear Information Bottleneck, 2018
⁵Alemi et al., "Deep Variational Information Bottleneck", 2017

How to Train your DNN (1)





Include decision rule (arg max, softmax, etc.) ⇒ P3
 Compression term may become useless/harmful

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How to Train your DNN (2)



- Train a stochastic
 DNN (e.g., add noise)
- Leads to robustness (P4)
- Encourages geometric clustering⁶ (P2)

⁶Goldfeld et al., Estimating Information Flow in Neural Networks, 2018

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How to Train your DNN (3)

From

$$\min_{\theta} I(X; L) - \beta I(Y; L)$$

to, e.g., cross-entropy and variational bounds.

- Replace IB functional by better-behaved cost function
- ▶ E.g., cross-entropy encourages P1 and P3
- Variational bounds may encourage geometric compression P2
- etc.

 $\min_{\theta} I(X; L) - \beta I(Y; L)$

Implemented approximations yield^{7,8,9,10}

- simple latent representation
- improved generalization
- adversarial robustness

⁷Kolchinsky, Tracey, and Wolpert, Nonlinear Information Bottleneck, 2018

⁸Alemi et al., "Deep Variational Information Bottleneck", 2017

⁹Banerjee and Montufar, The Variational Deficiency Bottleneck, 2018

¹⁰Alemi, Fischer, and Dillon, Uncertainty in the Variational Information Bottleneck, 2018

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It's the approximations that make the IB principle work!

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Conclusion

 IB principle is insufficient for training latent representations in deterministic DNNs

- infinite
- piecewise constant
- invariant under bijections
- ▶ Remedies available and backed by evidence:
 - enforce geometric (not IT) compression (P2) \implies P3
 - include the decoder \implies P3
 - introduce stochasticity \implies P4

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Thanks!

ReLU Activation Functions

IB functional is either

- infinite, or
- \blacktriangleright a piecewise constant function of θ



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