# How (Not) To Train Your DNN Using <br> The Information Bottleneck Functional 



## The Authors and Funders



## Neural Network for Classification



## Setup and Notation



- $Y \in \mathcal{Y}, \mathcal{Y}$ finite set
- $X \in \mathbb{R}^{N}$
- Joint distribution of $X, Y$ is known
- Encoder and decoder are deterministic, e.g.,

$$
L_{i+1}=\sigma\left(\mathbb{W}_{i}^{T} L_{i}+b_{i+1}\right)
$$

and $\theta=\left\{\mathbb{W}_{0}, \ldots, \mathbb{W}_{i-1}, b_{1}, \ldots, b_{i}\right\}$

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$$
\begin{aligned}
& \mathrm{P} 1 \Leftrightarrow \operatorname{large} I(Y ; L) \\
& \mathrm{P} 2 \Leftrightarrow \text { small } I(X ; L)
\end{aligned}
$$

IB Principle for Training DNN Classifier
IB principle for training DNNs ${ }^{1}$

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\min _{\theta} I(X ; L)-\beta I(Y ; L)
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Approximations yield ${ }^{2,3}$

- simple latent representation
- improved generalization
- adversarial robustness

taken from [2]

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$$
\text { Do we have }(P 1 \wedge P 2) \Longrightarrow(P 3 \wedge P 4) \text { ? }
$$

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- (Focus on $L$, architectural simplicity not considered)

Center
Computability

## Theorem

Let $X$ have a PDF $f_{X}$ that is continuous on $\mathcal{X} \subset \mathbb{R}^{N}$.

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Let $X$ have a PDF $f_{X}$ that is continuous on $\mathcal{X} \subset \mathbb{R}^{N}$. Let $\sigma$ be either bi-Lipschitz or continuously differentiable with strictly positive derivative. Then, for almost every choice of $\theta$, we have

$$
I(X ; L)=\infty .
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## Invariance under Bijections: No P3



## Invariance under Bijections: No P4



IB for Learning Representations - Summary

The IB functional

- is infinite for continuous input
- is piecewise constant in general
- does not encourage "simple" representations (P3)
- does not encourage robust representations (P4)

Why does it work? ${ }^{4,5}$

[^4]
## How to Train your DNN (1)



$$
\min _{\theta} I(X ; \hat{Y})-\beta I(Y ; \hat{Y})
$$

- Include decision rule (arg max, softmax, etc.) $\Longrightarrow$ P3
- Compression term may become useless/harmful


## How to Train your DNN (2)



- Train a stochastic DNN (e.g., add noise)
- Leads to robustness (P4)
- Encourages geometric clustering ${ }^{6}$ (P2)

[^5]
## How to Train your DNN (3)

From

$$
\min _{\theta} I(X ; L)-\beta I(Y ; L)
$$

to, e.g., cross-entropy and variational bounds.

- Replace IB functional by better-behaved cost function
- E.g., cross-entropy encourages P1 and P3
- Variational bounds may encourage geometric compression P2
- etc.


## IB Principle for Training DNN Classifier

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Implemented approximations yield ${ }^{7,8,9,10}$

- simple latent representation
- improved generalization
- adversarial robustness

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It's the approximations that make the IB principle work!

[^7]
## Conclusion

- IB principle is insufficient for training latent representations in deterministic DNNs
- infinite
- piecewise constant
- invariant under bijections
- Remedies available and backed by evidence:
- enforce geometric (not IT) compression (P2) $\Longrightarrow$ P3
- include the decoder $\Longrightarrow P 3$
- introduce stochasticity $\Longrightarrow \mathrm{P} 4$


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## Thanks!

## ReLU Activation Functions

IB functional is either

- infinite, or
- a piecewise constant function of $\theta$



[^0]:    ${ }^{1}$ Tishby and Zaslavsky, "Deep learning and the information bottleneck principle", 2015
    ${ }^{2}$ Kolchinsky, Tracey, and Wolpert, Nonlinear Information Bottleneck, 2018
    ${ }^{3}$ Alemi et al., "Deep Variational Information Bottleneck", 2017

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[^4]:    ${ }^{4}$ Kolchinsky, Tracey, and Wolpert, Nonlinear Information Bottleneck, 2018
    ${ }^{5}$ Alemi et al., "Deep Variational Information Bottleneck", 2017

[^5]:    ${ }^{6}$ Goldfeld et al., Estimating Information Flow in Neural Networks, 2018

[^6]:    ${ }^{7}$ Kolchinsky, Tracey, and Wolpert, Nonlinear Information Bottleneck, 2018
    ${ }^{8}$ Alemi et al., "Deep Variational Information Bottleneck", 2017
    ${ }^{9}$ Banerjee and Montufar, The Variational Deficiency Bottleneck, 2018
    ${ }^{10}$ Alemi, Fischer, and Dillon, Uncertainty in the Variational Information Bottleneck, 2018

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